



## $\alpha$ -Avoidance

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## 1. Motivation

## 2. $\alpha$ -Paths

## 3. $\alpha$ -Avoidance in different calculi

## 4. Soundness and Undecidability

## 5. Conclusion and Future Work

# Overview

## **1. Motivation**

## 2. $\alpha$ -Paths

## 3. $\alpha$ -Avoidance in different calculi

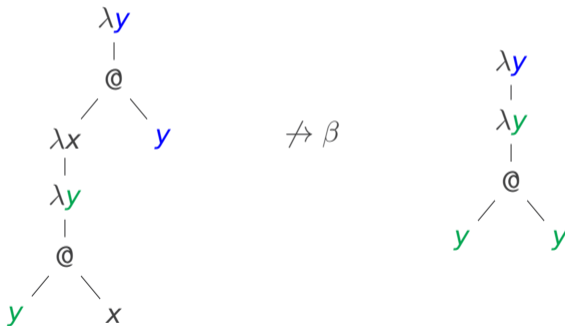
## 4. Soundness and Undecidability

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# Substitution and bindings

## $\beta$ -reduction in the $\lambda$ -calculus

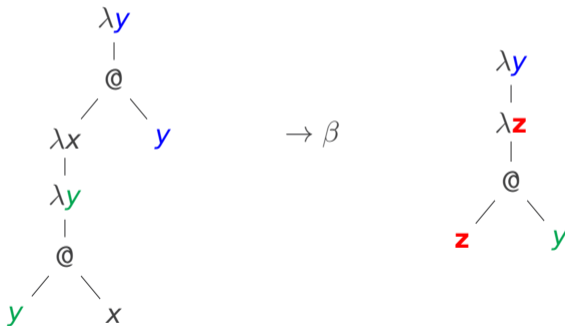
A variable capture may lead to inconsistent results.



# Substitution and bindings

## $\beta$ -reduction in the $\lambda$ -calculus

A variable capture may lead to inconsistent results.



# $\alpha$ -Avoidance

$$M \rightarrow_{\beta} N_1 \rightarrow_{\beta} \dots \rightarrow_{\beta} N_k$$

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$\xrightarrow{\beta}$ : ordinary  $\beta$ -step where we may (need to) apply  $\alpha$ .

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Can  $\alpha$ -conversion steps be avoided for a  $\lambda$ -term  $M$

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Can  $\alpha$ -conversion steps be avoided for a  $\lambda$ -term  $M$ , by suitably  $\alpha$ -converting it up front, say to a term  $M'$

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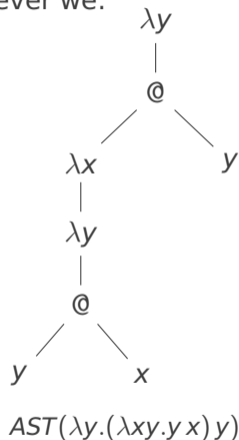
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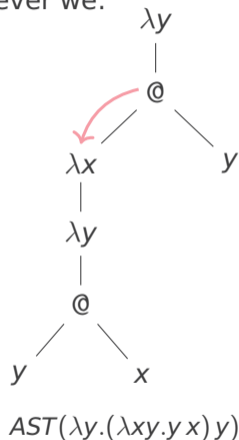
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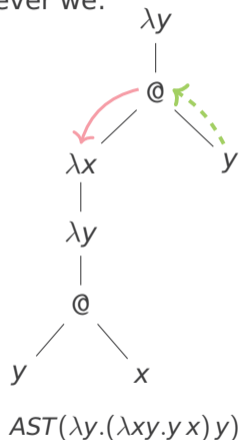
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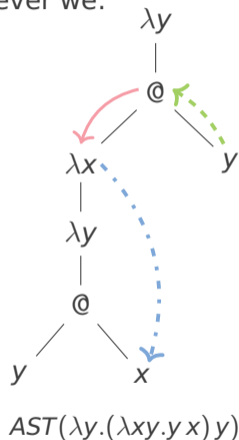
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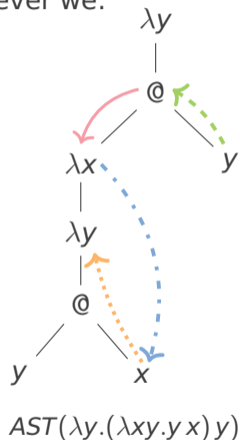
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(*c*-edge  $\dashrightarrow$ )



# $\alpha$ via paths

## *arbc* $\alpha$ -path

$x \dashrightarrow @ \xrightarrow{\quad} \lambda y \dashrightarrow y \dashrightarrow \lambda x$



# $\alpha$ via paths

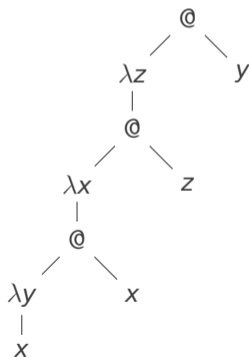
*arbc*  $\alpha$ -path

$x$   $\dashrightarrow$   $@$   $\longrightarrow$   $\lambda y$   $\dashrightarrow$   $y$   $\dashrightarrow$   $\lambda x$

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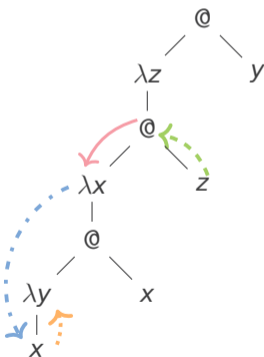


$(\lambda z. (\lambda x. (\lambda y. x) x) z) y$

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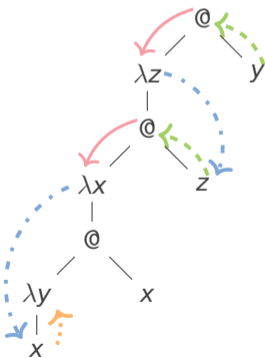


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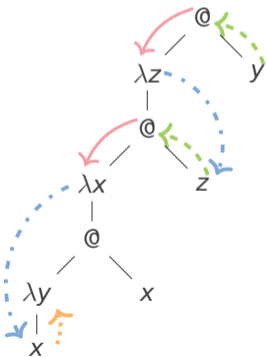


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$(arb)^i c$   $\alpha$ -path

$(x \dashrightarrow @ \xrightarrow{\quad} \lambda y \dashrightarrow y)^i \dashrightarrow \lambda x$

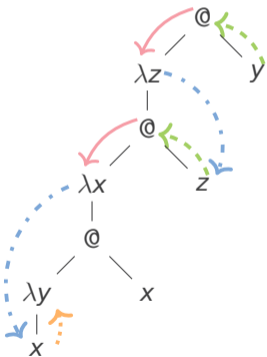


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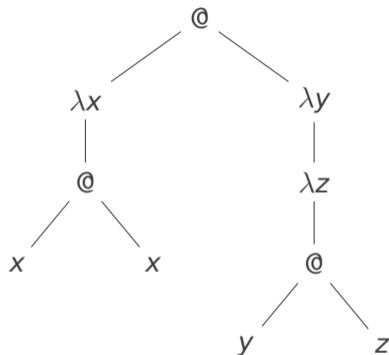
## $(arb)^i c$ $\alpha$ -path

$$(x \dashrightarrow @ \longrightarrow \lambda y \dashrightarrow y)^i \dashrightarrow \lambda x$$



$$\begin{aligned} & \frac{(\lambda z. (\lambda x. (\lambda y. x) x) z) y}{\lambda x. (\lambda y. x) x} \\ \rightarrow_{\beta} & \frac{(\lambda x. (\lambda y. x) x) y}{(\lambda y'. y) x} \\ \rightarrow_{\beta} & y \end{aligned}$$

# $\alpha$ via paths

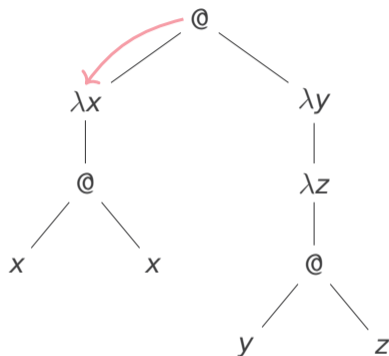


$(\lambda x.x x) (\lambda yz.y z)$

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$(x \dashrightarrow @ \rightarrow \lambda y \dashrightarrow y)^+ \dashrightarrow \lambda x$

# $\alpha$ via paths



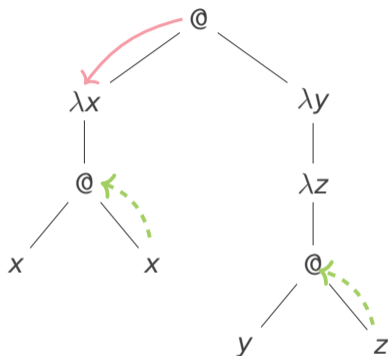
$(\lambda x.x x) (\lambda yz.y z)$

$(arb)^i c$   $\alpha$ -path

$(x \dashrightarrow @ \xrightarrow{\text{red}} \lambda y \dashrightarrow y)^+ \dashrightarrow \lambda x$



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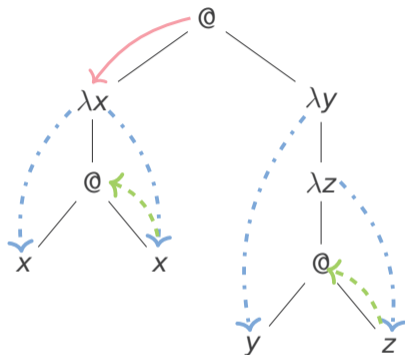


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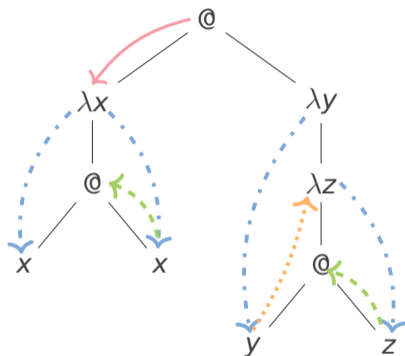


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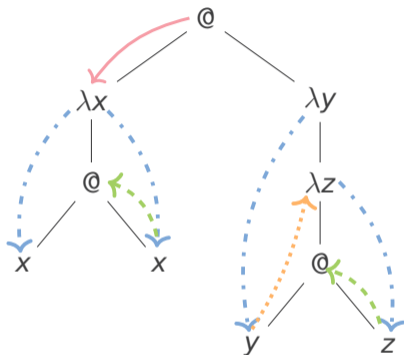


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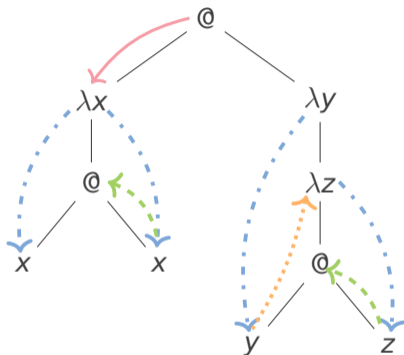


$$\rightarrow_{\beta} \frac{(\lambda x.x x) (\lambda yz.y z)}{(\lambda yz.y z) (\lambda yz.y z)}$$

$(arb)^i c$   $\alpha$ -path

$$(x \text{ --- } \rightarrow \text{---} @ \text{ --- } \rightarrow \text{---} \lambda y \text{ --- } \rightarrow \text{---} y)^+ \text{ --- } \rightarrow \text{---} \lambda x$$

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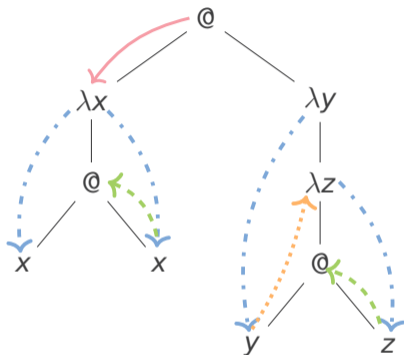


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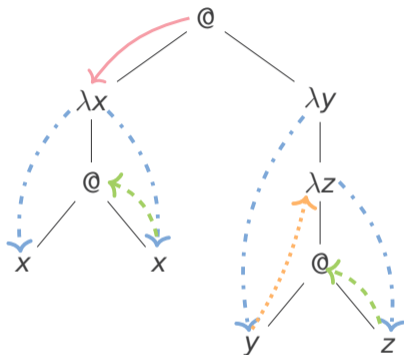


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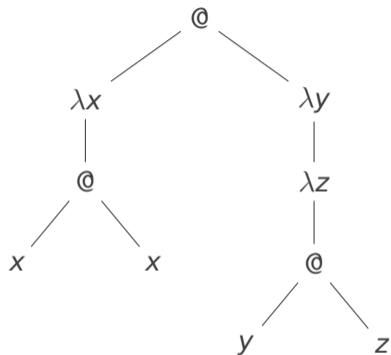
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need characterisation of created redexes

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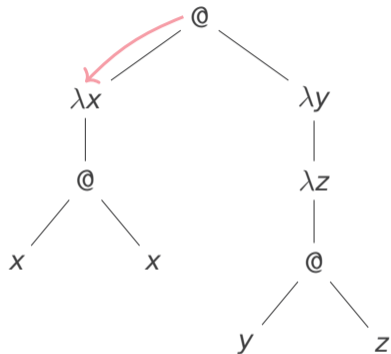
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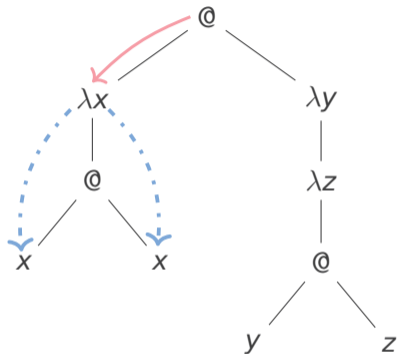


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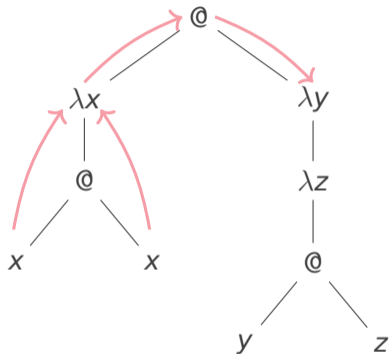
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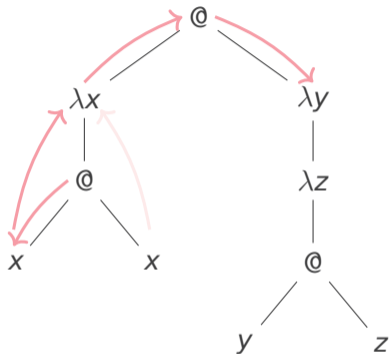
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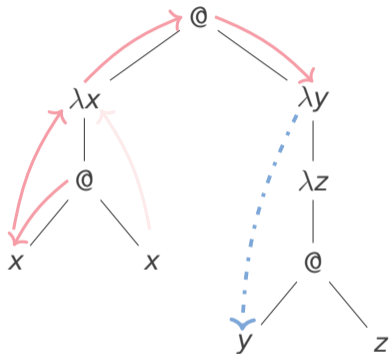
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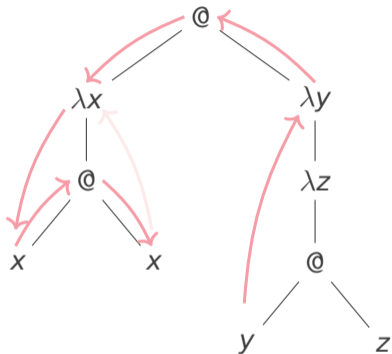
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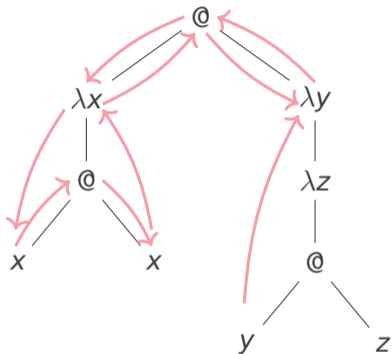
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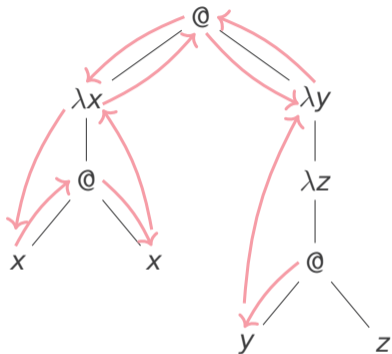
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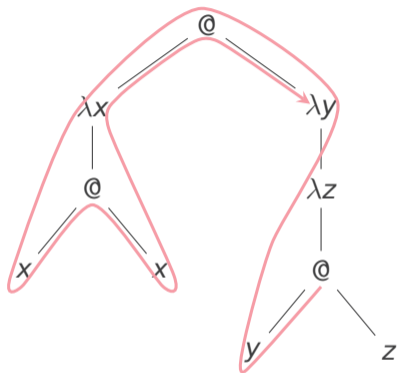
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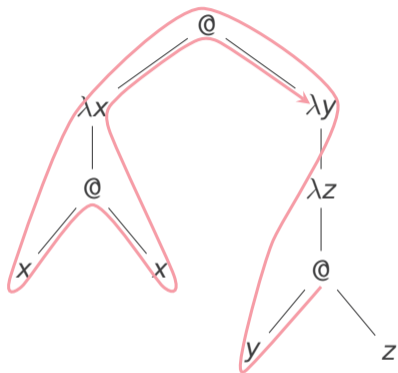


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## Legal paths (Asperti et al. 1994)

Characterise virtual redexes.

# Created redexes



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# Overview

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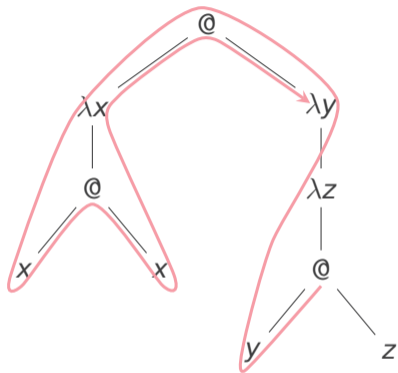
**2.  $\alpha$ -Paths**

**3.  $\alpha$ -Avoidance in different calculi**

**4. Soundness and Undecidability**

**5. Conclusion and Future Work**

# $\alpha$ -Paths

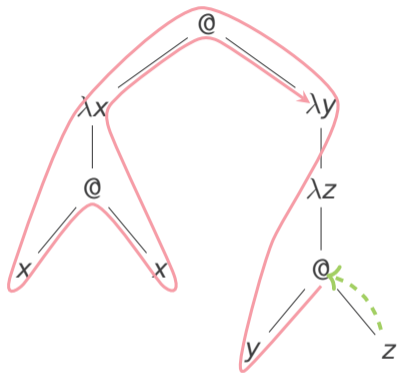


$$\begin{aligned} & (\lambda x. x x) (\lambda y z. y z) \\ \rightarrow_{\beta} & \underline{(\lambda y z. y z) (\lambda y z. y z)} \\ \rightarrow_{\beta} & \lambda z. \underline{(\lambda y z. y z) z} \\ \rightarrow_{\beta} & \lambda z. (\lambda z'. z z') \end{aligned}$$

**Combining  $a$ -,  $b$ - and  $c$ -edges with legal paths  $\implies (alb)^i c$   $\alpha$ -path**

Allows the prediction of the potential need for  $\alpha$ .

# $\alpha$ -Paths

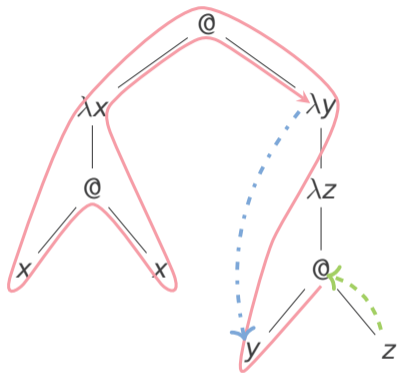


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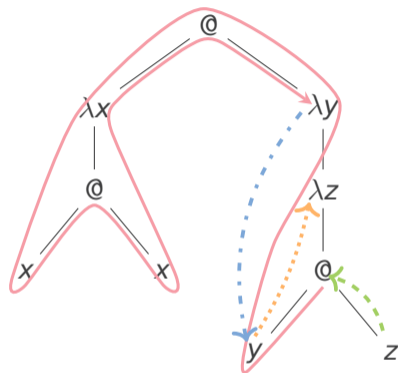


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**Combining  $a$ -,  $b$ - and  $c$ -edges with legal paths  $\implies (alb)^i c$   $\alpha$ -path**

Allows the prediction of the potential need for  $\alpha$ .

# $\alpha$ -Paths

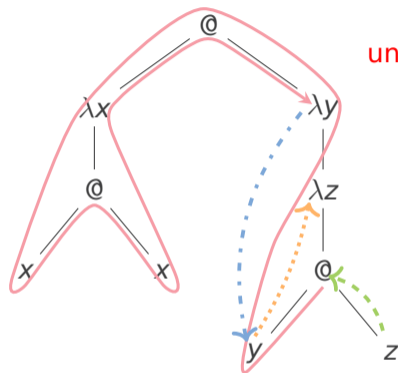


$$\begin{aligned}
 & \underline{(\lambda x. x x) (\lambda y z. y z)} \\
 \rightarrow_{\beta} & \underline{(\lambda y z. y z) (\lambda y z. y z)} \\
 \rightarrow_{\beta} & \lambda z. \underline{(\lambda y z. y z) z} \\
 \rightarrow_{\beta} & \lambda z. (\lambda z'. z z')
 \end{aligned}$$

**Combining  $a$ -,  $b$ - and  $c$ -edges with legal paths  $\implies (alb)^i c$   $\alpha$ -path**

Allows the prediction of the potential need for  $\alpha$ .

# $\alpha$ -Paths



unremovable

$$\begin{aligned}
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 \rightarrow_{\beta} & \underline{(\lambda yz.y z) (\lambda yz.y z)} \\
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 \rightarrow_{\beta} & \lambda z. (\lambda z'.z z')
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Allows the prediction of the potential need for  $\alpha$ .



# $\alpha$ -Avoidance

## Question

Can  $\alpha$ -conversion steps be avoided for a  $\lambda$ -term  $M$ , by suitably  $\alpha$ -converting it up front, say to a term  $M'$  such that no  $\alpha$ -conversion step needs to be invoked along any reduction from  $M'$ .

$$M \rightarrow_{\beta} N_1 \rightarrow_{\beta} \dots \rightarrow_{\beta} N_k$$

$$\equiv_{\alpha} \quad \quad \quad \equiv_{\alpha} \quad \quad \quad \equiv_{\alpha}$$

$$M' \rightarrow_{\beta_{naive}} N'_1 \rightarrow_{\beta_{naive}} \dots \rightarrow_{\beta_{naive}} N'_k$$

$\rightarrow_{\beta}$ : ordinary  $\beta$ -step where we may (need to) apply  $\alpha$ .

$\rightarrow_{\beta_{naive}}$ : naïve  $\beta$ -step with naïve substitution (no  $\alpha$ ).

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$$\begin{array}{ccccccc} \text{\color{red}\mathit{\alpha}\text{-paths}} & M & \rightarrow_{\beta} & N_1 & \rightarrow_{\beta} \dots \rightarrow_{\beta} & N_k \\ & \equiv_{\alpha} & & \equiv_{\alpha} & & \equiv_{\alpha} \end{array}$$

$$\text{\color{green}\mathit{no } \alpha\text{-paths}} \quad M' \rightarrow_{\beta_{naive}} N'_1 \rightarrow_{\beta_{naive}} \dots \rightarrow_{\beta_{naive}} N'_k$$

$\rightarrow_{\beta}$ : ordinary  $\beta$ -step where we may (need to) apply  $\alpha$ .

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# Overview

1. Motivation

2.  $\alpha$ -Paths

**3.  $\alpha$ -Avoidance in different calculi**

4. Soundness and Undecidability

5. Conclusion and Future Work

# $\alpha$ -Avoidance in different calculi

## $\lambda$ -calculus

$\alpha$  is unavoidable

$$\begin{aligned} & \underline{(\lambda x. x x) (\lambda y \lambda z. y z)} \\ \rightarrow_{\beta} & \underline{(\lambda y \lambda z. y z) (\lambda y \lambda z. y z)} \\ \rightarrow_{\beta} & \lambda z. \underline{(\lambda y \lambda z. y z) z} \\ \rightarrow_{\alpha} & \lambda z. \underline{(\lambda y. \lambda z'. y z')} z \\ \rightarrow_{\beta} & \lambda z \lambda z'. z z' \end{aligned}$$

# $\alpha$ -Avoidance in different calculi

## $\lambda$ -calculus

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$$\begin{aligned} & \frac{(\lambda x. x x) (\lambda y \lambda z. y z)}{\rightarrow_{\beta} (\lambda y \lambda z. y z) (\lambda y \lambda z. y z)} \quad \left. \vphantom{\frac{(\lambda x. x x) (\lambda y \lambda z. y z)}{\rightarrow_{\beta} (\lambda y \lambda z. y z) (\lambda y \lambda z. y z)}}} \right\} \text{duplication} \\ & \rightarrow_{\beta} \lambda z. (\lambda y \lambda z. y z) z \\ & \rightarrow_{\alpha} \lambda z. (\lambda y. \lambda z'. y z') z \\ & \rightarrow_{\beta} \lambda z \lambda z'. z z' \end{aligned}$$

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$$\begin{aligned} & \frac{(\lambda x. x x) (\lambda y \lambda z. y z)}{\rightarrow_{\beta} (\lambda y \lambda z. y z) (\lambda y \lambda z. y z)} && \left. \begin{array}{l} \text{duplication} \\ \text{redex creation} \end{array} \right\} \\ & \rightarrow_{\beta} \lambda z. (\lambda y \lambda z. y z) z \\ & \rightarrow_{\alpha} \lambda z. (\lambda y. \lambda z'. y z') z \\ & \rightarrow_{\beta} \lambda z \lambda z'. z z' \end{aligned}$$

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**3 phenomena causing  $\alpha$  – absence of each allows to avoid  $\alpha$**

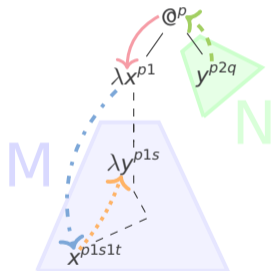
i.e. we always can  $\alpha$ -rename up front such that no  $\alpha$ -paths occur



# $\alpha$ -Avoidance in different calculi

**Developments are  $\alpha$ -avoiding (Church and Rosser 1936)**

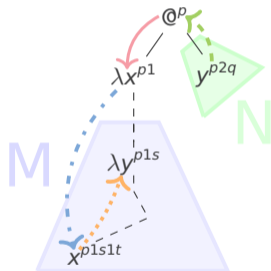
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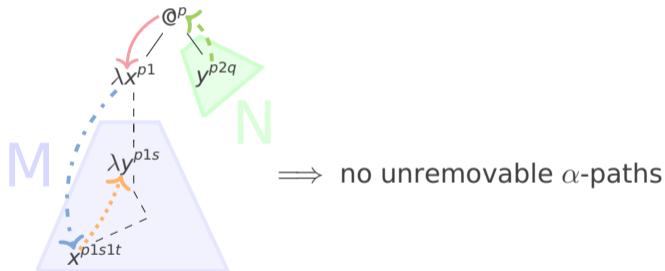
Final  $\lambda x$ -node at the left of the starting variable  $x$

$$(x^{p2q} \text{ --- } @^p \text{ --- } \lambda y^{p1} \text{ --- } y^{p1s1t}) + \dots \lambda x^{p1s}$$

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# $\alpha$ -Avoidance in different calculi

## **The linear (affine) $\lambda$ -calculus (Hindley 1989)**

Forbids duplication by restricting term-formation

# $\alpha$ -Avoidance in different calculi

## The linear (affine) $\lambda$ -calculus (Hindley 1989)

Forbids duplication by restricting term-formation

### Lemma 19.

Let  $M$  be a linear  $\lambda$ -term,  $M \rightarrow_{\beta} N$  and  $q \prec p$  for some positions  $p, q$  in  $M$ . If  $p \blacktriangleright p'$  and  $q \blacktriangleright q'$ , then  $q' \prec p'$ .

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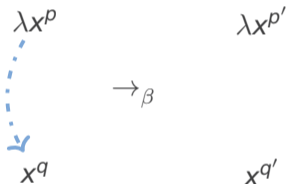
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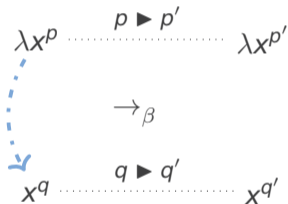
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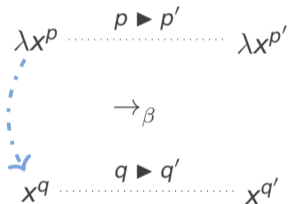
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context	$p \triangleright p$	if $o$ is not prefix of $p$
body	$o11p \triangleright op$	if $p \neq \epsilon$ and $p \neq q$
arg	$o2p \triangleright oqp$	for all positions $q$ , such that $o11q$ is bound by $o1$

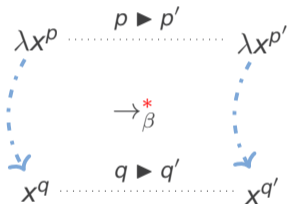
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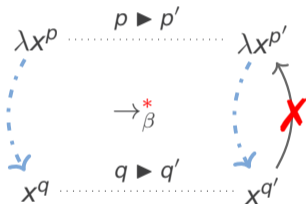
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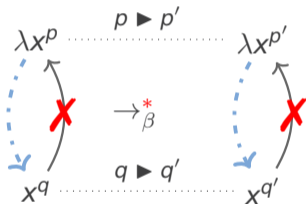
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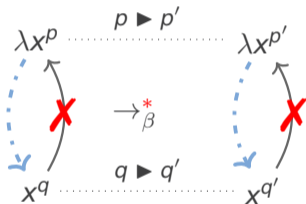
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$\implies$  no unremovable  $\alpha$ -paths

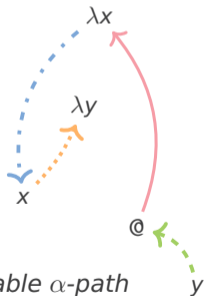
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## The weak $\lambda$ -calculus (Çağman and Hindley 1998)

Forbids to contract open redexes

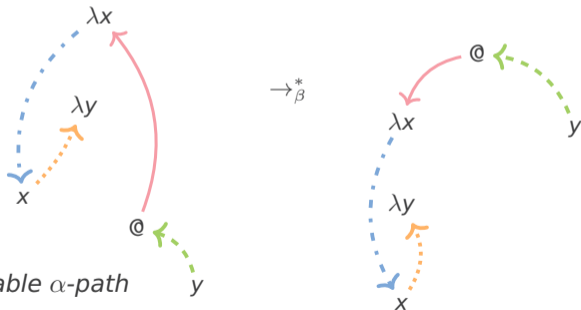


*a term with an unremovable  $\alpha$ -path*

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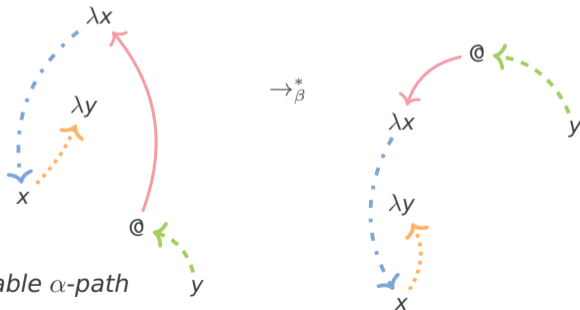
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“bound variables are never released”



*a term with an unremovable  $\alpha$ -path*

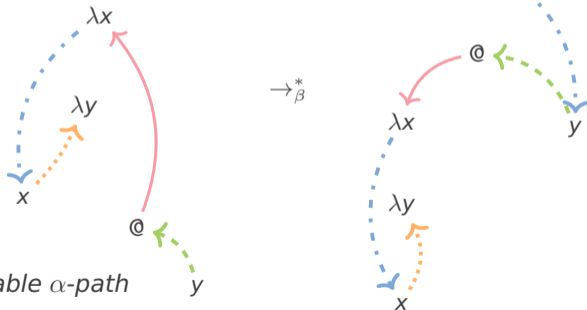


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Forbids to contract open redexes

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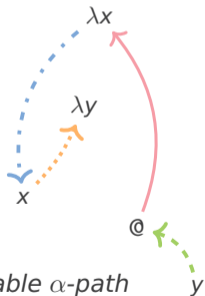
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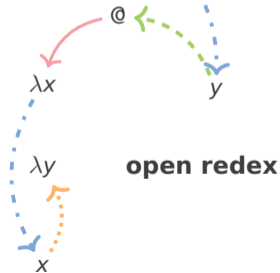
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*a term with an unremovable  $\alpha$ -path*

$\rightarrow_{\beta}^*$

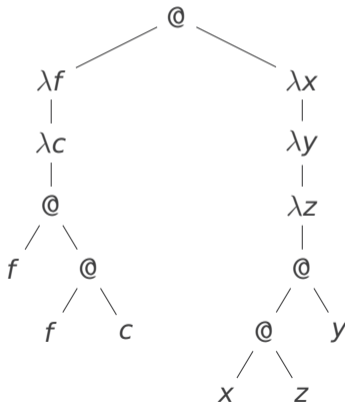


# $\alpha$ -Avoidance in different calculi

## The simply-typed $\lambda$ -calculus à la Church

$\alpha$  is unavoidable

$$(\lambda f^{\tau \rightarrow \tau} x^{\sigma} . f (f x)) (\lambda x^{\tau} y^{\sigma} z^{\sigma} . x z y)$$



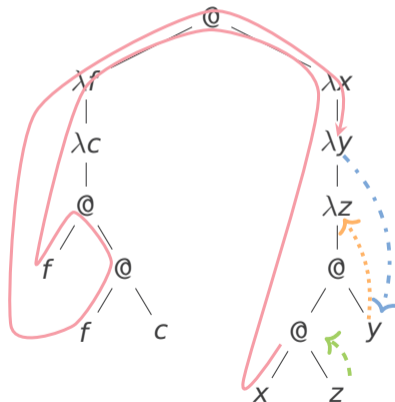
$$\sigma = 0, \tau = 0 \rightarrow 0 \rightarrow 0$$

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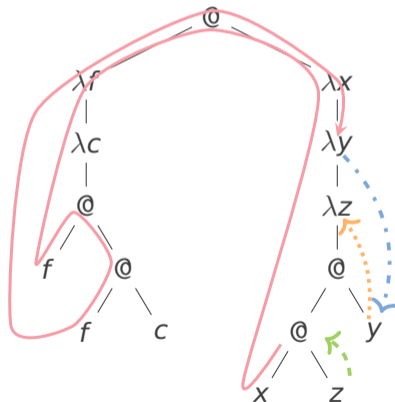
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# $\alpha$ -Avoidance in different calculi

## The safe $\lambda$ -calculus (Blum and Ong 2007)

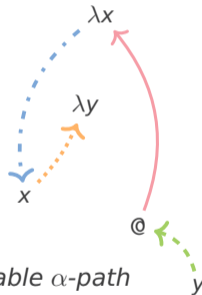
safety: if  $x \in \mathcal{FV}(M)$ , then  $\text{ord } M \leq \text{ord } x$ .

$\text{ord } o := 0$

$\text{ord } \sigma \rightarrow \tau := \max(1 + \text{ord } \sigma, \text{ord } \tau)$

$\text{ord } y \geq \text{ord } x$

$\text{ord } (\lambda y.t) \leq \text{ord } x$



*a term with an unremovable  $\alpha$ -path*



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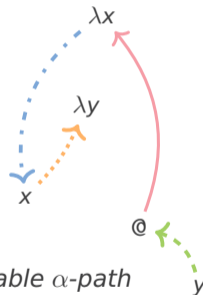
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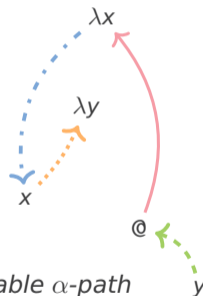
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$\color{red}\lightning \implies$  no  $\alpha$ -paths



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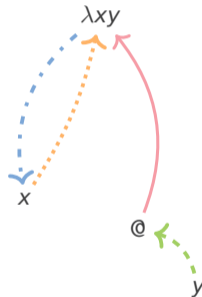
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safety + combined abstractions and simultaneous substitution.

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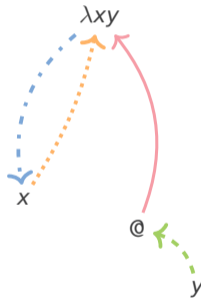
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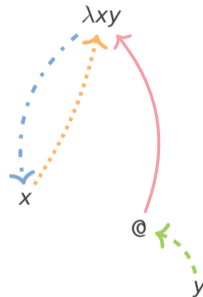
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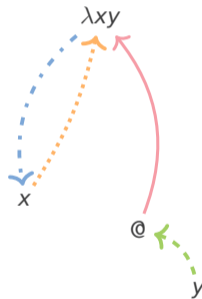
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$ord\ y \not\geq ord\ x$



# $\alpha$ -Avoidance in different calculi

## The safe $\lambda$ -calculus (Blum and Ong 2007)

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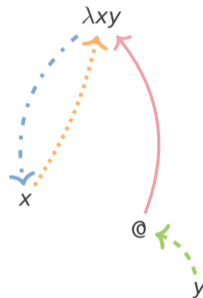
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$\implies$  cannot exclude variable capture  
a more restrictive system needed





# Overview

1. Motivation

2.  $\alpha$ -Paths

3.  $\alpha$ -Avoidance in different calculi

**4. Soundness and Undecidability**

5. Conclusion and Future Work

# Soundness, but not completeness

**variable capture**  $\implies$   $\alpha$ -path

Proven in our paper



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$(\lambda x.x x) (\lambda y x.y z)$  is  $\alpha$ -free

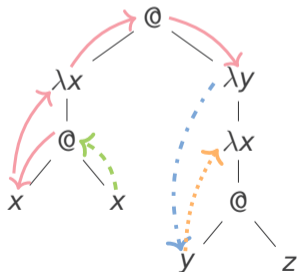
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$$\begin{aligned} & (\lambda x.x x) (\lambda y x.y z) \\ \rightarrow_{\beta} & \frac{(\lambda y x.y z) (\lambda y x.y z)}{(\lambda y x.y z) (\lambda y x.y z)} \\ \rightarrow_{\beta} & \lambda x. (\lambda y x.y z) z \\ \rightarrow_{\beta} & \lambda x. (\lambda x.z z) \end{aligned}$$

# Undecidability

## Reduction from Post's correspondence problem (Post 1946)

$\alpha$ -avoidance is undecidable for the leftmost–outermost reduction strategy.

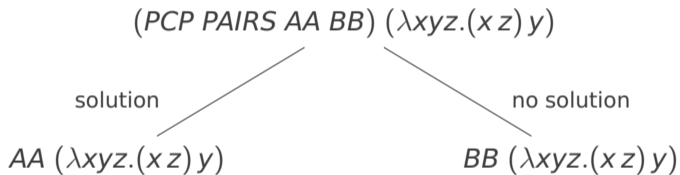
$(PCP\ PAIRS\ AA\ BB)\ (\lambda xyz.(xz)y)$

$AA \dots$  encoding of string "aa"       $BB \dots$  encoding of string "bb"

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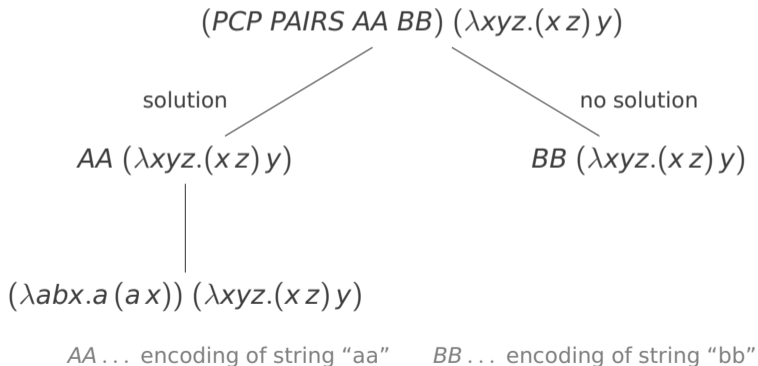
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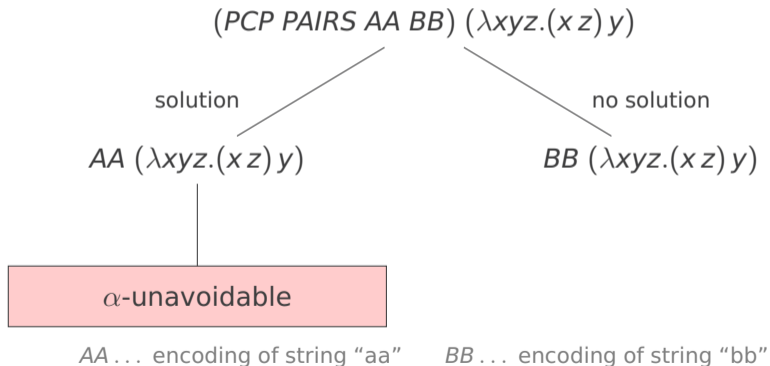
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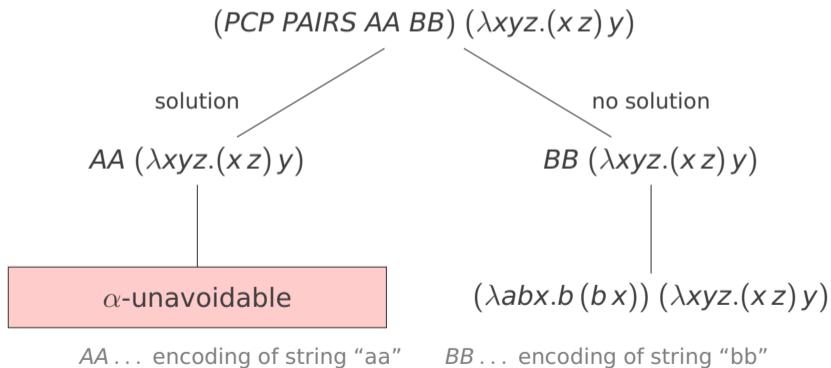




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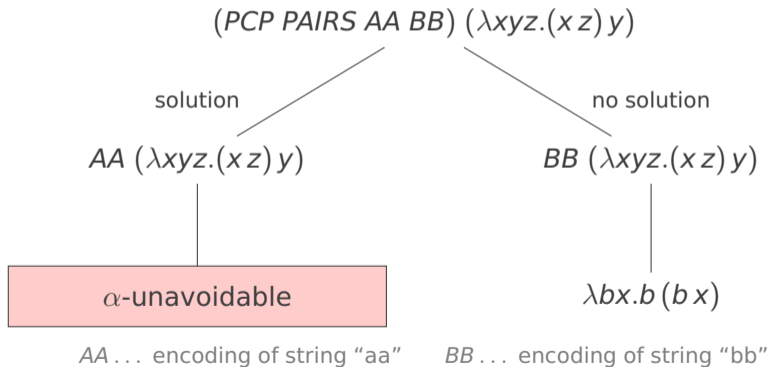
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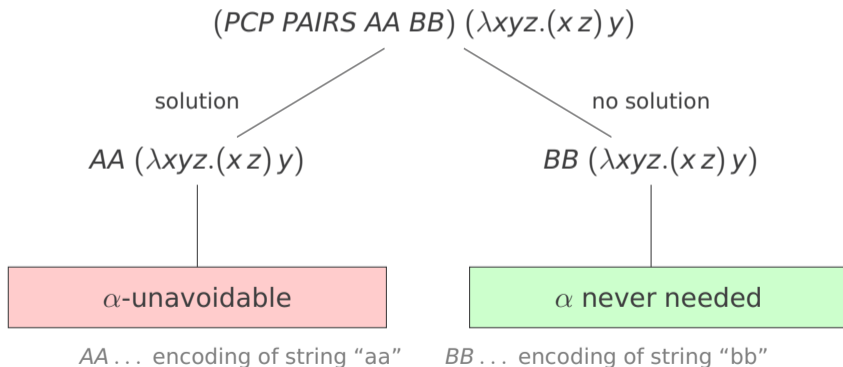
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# $\alpha$ -Avoidance – Tool

## Alpha Avoidance

Untyped Term:

`(/x.x x) (/y z.y z)`

UT = (UT) | /x ... y.UT | UT ... UT | x

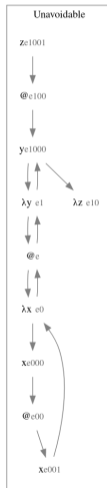
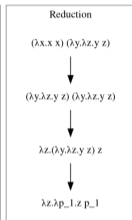
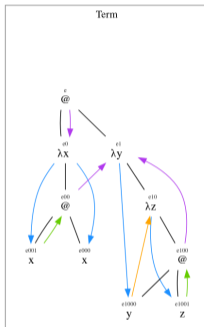
Max depth:

16

Analyze

- **Variable capture:** Yes, unavoidable
- **Safe naming:** Yes.
- **Typable:** Not Typable.
- **Linear:** No.

Samuel Frontull / Georg Moser / Vincent van Oostrom



Term: `(/x.x x) (/y z.y z)`

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Try it out:  
<http://195.201.17.253:5050/>

Reduction

$\lambda z.(\lambda y.\lambda z.y z) z$

$\lambda z.\lambda p_1.z p_1$

Unavoidable

$y e1000$

$\lambda y e1$

$\lambda z e10$

$@e$

$\lambda x e0$

$x e000$

$@e00$

$x e001$

Term: `(/x.x x) (/y z.y z)`

# Conclusion & Future Work

## Known results...

from a new perspective/novel approach

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## Undecidability

Do we have general undecidability of  $\alpha$ -avoidance?


## Alpha “circumvention”

Given some  $\lambda$ -term  $M$ , find a maximal reduction sequence where  $\alpha$  is never needed.



Thank you for your attention!

# Reference

-  Samuel Frontull, Georg Moser, and Vincent van Oostrom. “ $\alpha$ -Avoidance”. In: 8th International Conference on Formal Structures for Computation and Deduction (FSCD 2023). Ed. by Marco Gaboardi and Femke van Raamsdonk. Vol. 260. Leibniz International Proceedings in Informatics (LIPIcs). Dagstuhl, Germany: Schloss Dagstuhl – Leibniz-Zentrum für Informatik, 2023, 22:1–22:22. ISBN: 978-3-95977-277-8. URL: <https://drops.dagstuhl.de/opus/volltexte/2023/18006>.



# The safe $\lambda$ -calculus

## Claim, assuming the safe variable naming convention

Variable capture is guaranteed not to happen (Blum and Ong 2009).

$$\begin{array}{l} \text{(var)} \frac{}{x : A \vdash_s x : A} \quad \text{(const)} \frac{}{\vdash_s f : A} \quad f : A \in \Xi \quad \text{(wk)} \frac{\Gamma \vdash_s M : A}{\Delta \vdash_s M : A} \quad \Gamma \subset \Delta \quad \text{(\delta)} \frac{\Gamma \vdash_s M : A}{\Gamma \vdash_{asa} M : A} \\ \\ \text{(app}_{asa}\text{)} \frac{\Gamma \vdash_{asa} M : A \rightarrow B \quad \Gamma \vdash_s N : A}{\Gamma \vdash_{asa} M N : B} \quad \text{(app)} \frac{\Gamma \vdash_{asa} M : A \rightarrow B \quad \Gamma \vdash_s N : A}{\Gamma \vdash_s M N : B} \quad \text{ord } B \leq \text{ord } \Gamma \\ \\ \text{(abs)} \frac{\Gamma, x_1 : A_1, \dots, x_n : A_n \vdash_{asa} M : B}{\Gamma \vdash_s \lambda x_1^{A_1} \dots x_n^{A_n}. M : (A_1, \dots, A_n, B)} \quad \text{ord } (A_1, \dots, A_n, B) \leq \text{ord } \Gamma \end{array}$$

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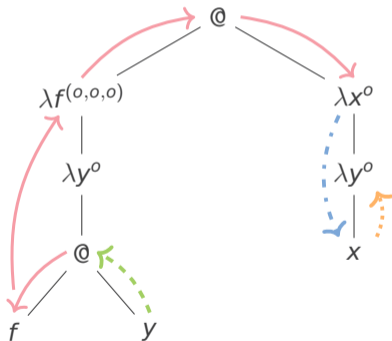
A term where  $\alpha$  is needed can be derived:  $\vdash_s (\lambda f^{(o,o,o)} y^o. f y) (\lambda x^o y^o. x)$

$(\lambda f y. f y) (\lambda x y. x) \rightarrow_{\beta_{sim}} \lambda y. (\lambda x y. x) y \rightarrow_{\beta_{sim}} \lambda y. \lambda y'. y$

# The safe $\lambda$ -calculus

**Counterexample:**  $\vdash_s (\lambda f^{(0,0,0)} y^0 . f y) (\lambda x^0 y^0 . x)$

$\alpha$  is needed although the term is safe and the naming convention is followed.





# The safe $\lambda$ -calculus

## Solution

A more restrictive set of rules forbidding "almost-safe" constructions.

$$\begin{aligned} & (var) \frac{}{\{x : A\} \vdash_{s\alpha} x : A} \quad (const) \frac{}{\vdash_{s\alpha} f : A} \quad f : A \in \Xi \quad (wk) \frac{\Gamma' \vdash_{s\alpha} M : A}{\Gamma \vdash_{s\alpha} M : A} \quad \Gamma' \subset \Gamma \\ & (app) \frac{\Gamma \vdash_{s\alpha} M : (A_1, \dots, A_n, B) \quad \Gamma_{\geq m} \vdash_{s\alpha} N_1 : A_1 \quad \dots \quad \Gamma_{\geq m} \vdash_{s\alpha} N_j : B_j}{\Gamma \vdash_{s\alpha} M N_1 \dots N_j : B} \quad m = ord B \\ & (abs) \frac{\Gamma_{\geq m} \cup \{x_1 : A_1, \dots, x_n : A_n\} \vdash_{s\alpha} M : B}{\Gamma \vdash_{s\alpha} \lambda x_1 \dots x_n. M : (A_1, \dots, A_n, B)} \quad m = ord (A_1, \dots, A_n, B) \end{aligned}$$

## Long-safety

These rules correspond to the typing rules for long-safe terms (Blum 2009; Blum and Ong 2009).

# Naïve $\beta$ -step

$M$	$\llbracket x := N \rrbracket$ (capture-avoiding)	$[x := N]$ (capture-permitting)
$x$	$N$	$N$
$y$	$y$	$y$
$e_1 e_2$	$e_1 \llbracket x := N \rrbracket e_2 \llbracket x := N \rrbracket$	$e_1 [x := N] e_2 [x := N]$
$\lambda x.e$	$\lambda x.e$	$\lambda x.e$
$\lambda y.e$	$\lambda y.e \llbracket x := N \rrbracket$ if $y \notin \mathcal{FV}(N)$ $\lambda z.e \llbracket y := z \rrbracket \llbracket x := N \rrbracket$ else with $z$ fresh for $e$ and $N$ .	$\lambda y.e[x := N]$

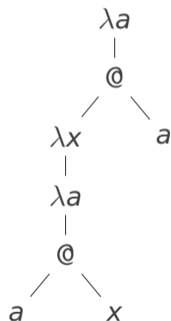
## Definition

$$(\lambda x.M) N \rightarrow_{\beta_{naive}} M[x := N]$$

# Variable names are irrelevant

## De Bruijn's lambda notation (Bruijn 1972)

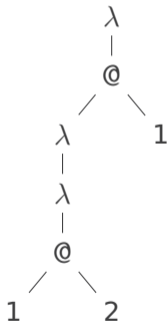
Exclusively work with (representatives of)  $\alpha$ -equivalence classes of  $\lambda$ -terms



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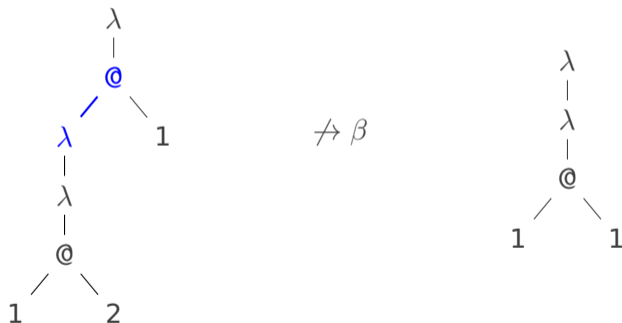
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